



Self-Learning Systems for Cyber Security

Kim Hammar & Rolf Stadler

kimham@kth.se, stadler@kth.se
KTH Royal Institute of Technology

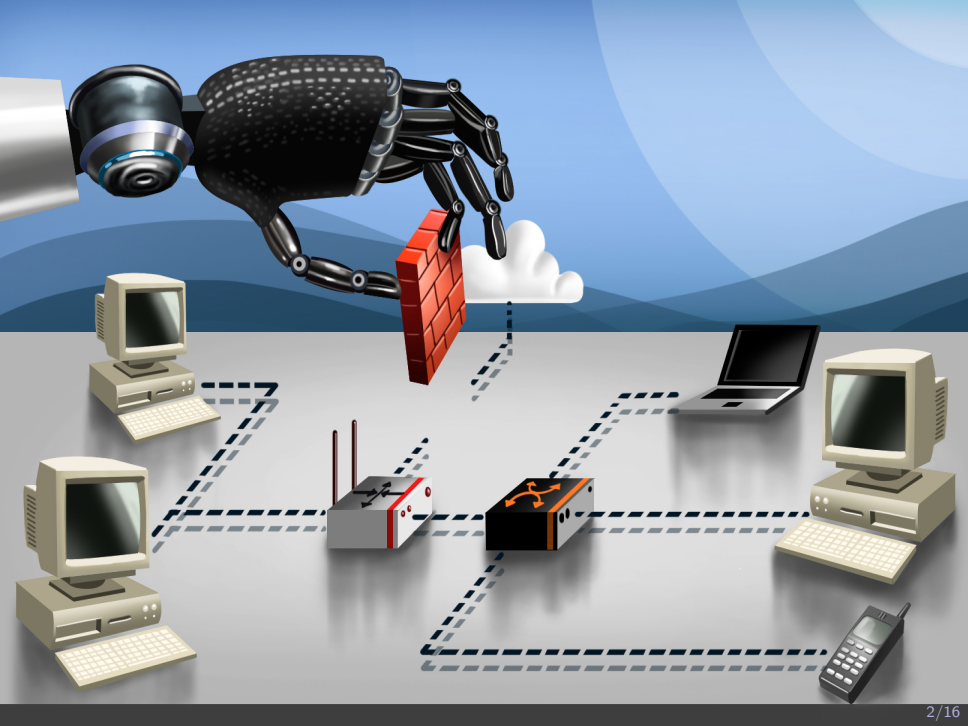
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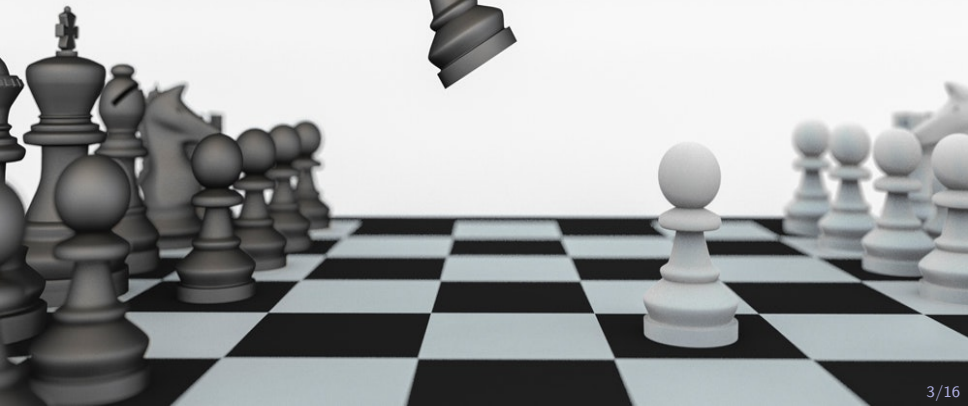
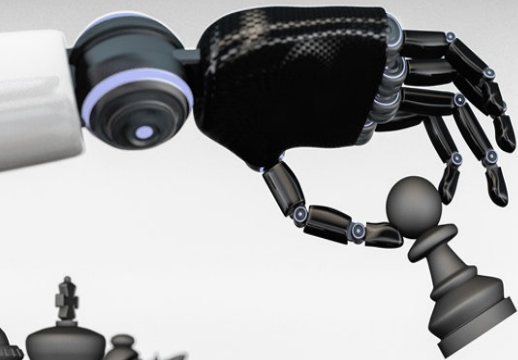


FÖRSVARSMAKTEN



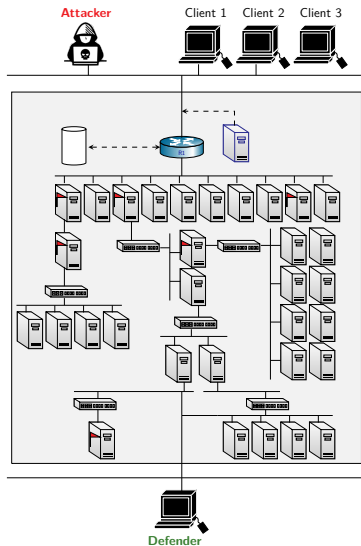
Förvarshögskolan





Challenges: Evolving and Automated Attacks

- ▶ **Challenges:**
 - ▶ Evolving & automated attacks
 - ▶ Complex infrastructures



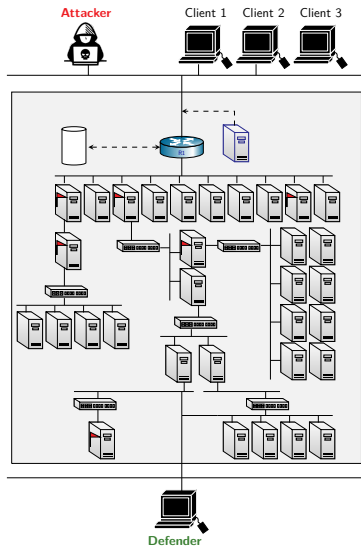
Goal: Automation and Learning

▶ Challenges

- ▶ Evolving & automated attacks
- ▶ Complex infrastructures

▶ Our Goal:

- ▶ Automate security tasks
- ▶ Adapt to changing attack methods



Approach: Game Model & Reinforcement Learning

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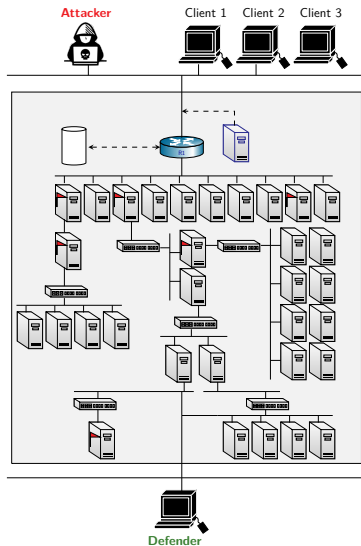
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▶ Our Approach:

- ▶ Model network attack and defense as *games*.
- ▶ Use *reinforcement learning* to learn policies.
- ▶ Incorporate learned policies in *self-learning systems*.



State of the Art

▶ Game-Learning Programs:

- ▶ TD-Gammon, AlphaGo Zero¹, OpenAI Five etc.
- ▶ \implies Impressive empirical results of *RL and self-play*

▶ Attack Simulations:

- ▶ Automated threat modeling², automated intrusion detection etc.
- ▶ \implies Need for *automation* and better security tooling

▶ Mathematical Modeling:

- ▶ Game theory³
- ▶ Markov decision theory
- ▶ \implies Many security operations involves *strategic decision making*

¹David Silver et al. "Mastering the game of Go without human knowledge". In: *Nature* 550 (Oct. 2017), pp. 354-. URL: <http://dx.doi.org/10.1038/nature24270>.

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³Tansu Alpcan and Tamer Basar. *Network Security: A Decision and Game-Theoretic Approach*. 1st. USA: Cambridge University Press, 2010. ISBN: 0521119324.

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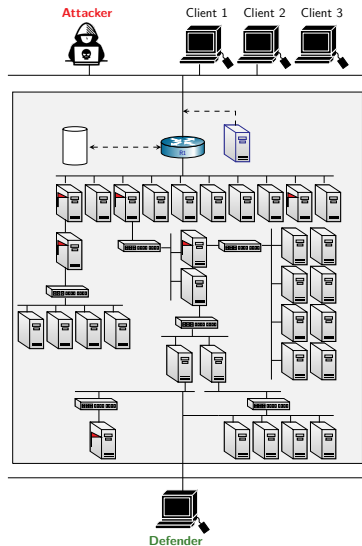
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Our Work

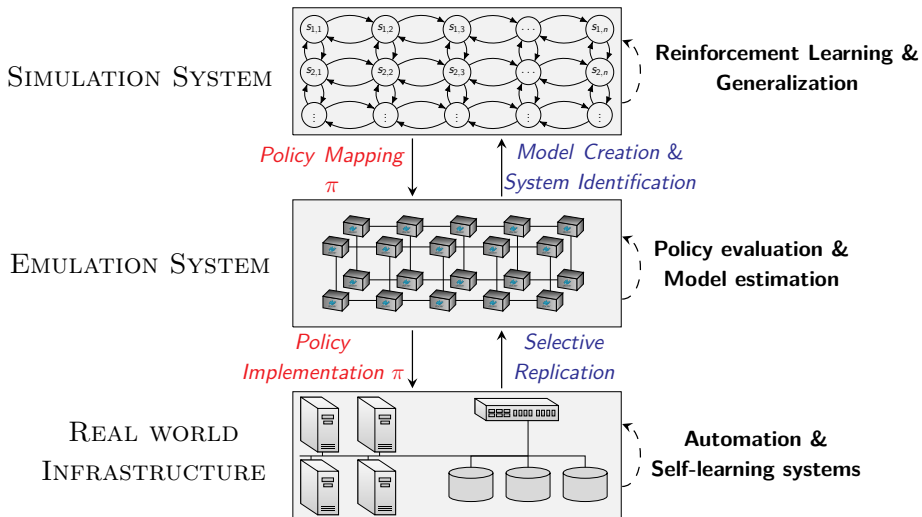
- ▶ **Use Case:** Intrusion Prevention
- ▶ **Our Method:**
 - ▶ Emulating computer infrastructures
 - ▶ System identification and model creation
 - ▶ Reinforcement learning and generalization
- ▶ **Results:** Learning to Capture The Flag
- ▶ **Conclusions and Future Work**

Use Case: Intrusion Prevention

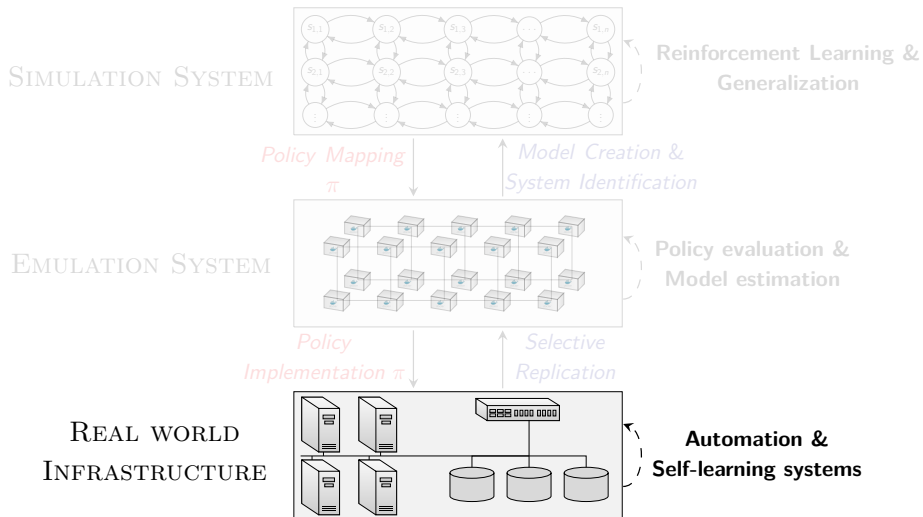
- ▶ A **Defender** owns an infrastructure
 - ▶ Consists of connected components
 - ▶ Components run network services
 - ▶ Defender *defends the infrastructure by monitoring and patching*
- ▶ An **Attacker** seeks to intrude on the infrastructure
 - ▶ Has a partial view of the infrastructure
 - ▶ Wants to compromise specific components
 - ▶ *Attacks by reconnaissance, exploitation and pivoting*



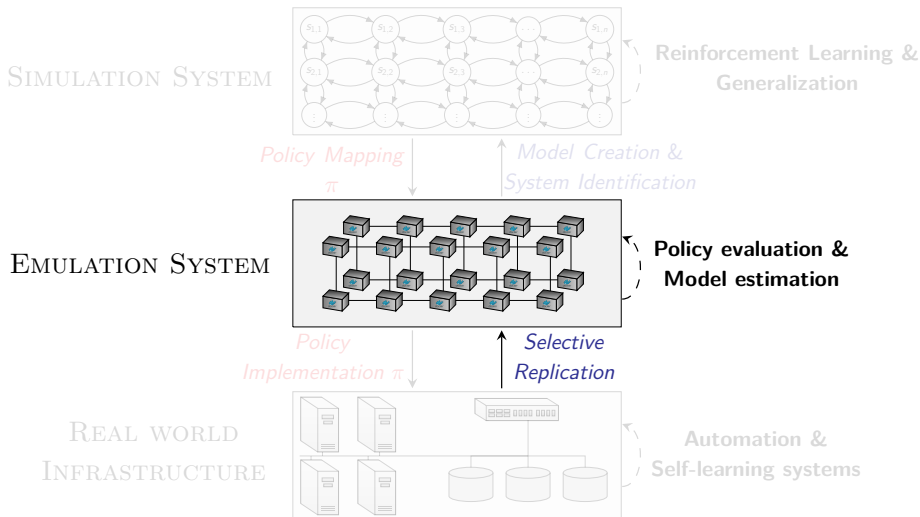
Our Method for Finding Effective Security Strategies



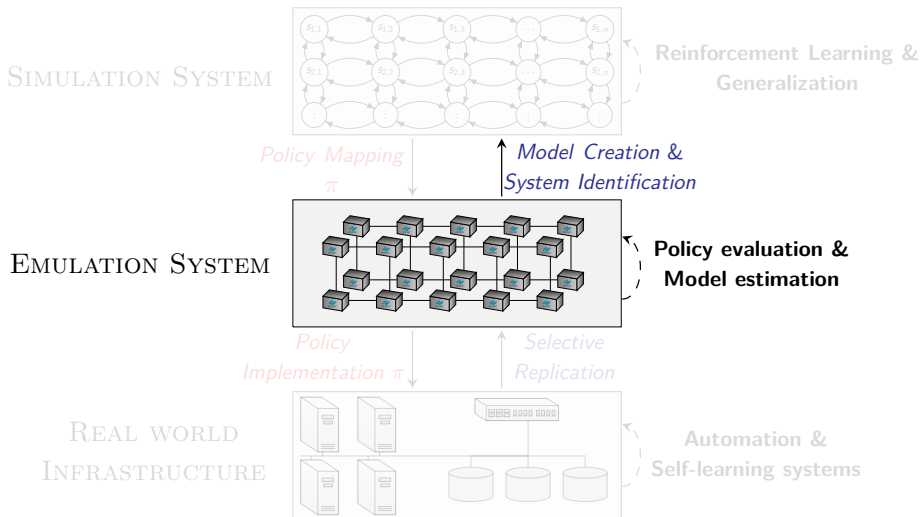
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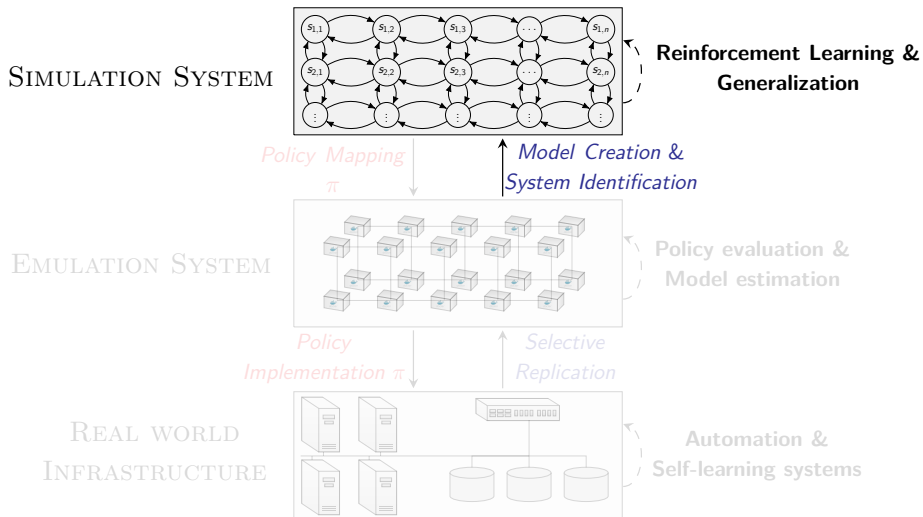
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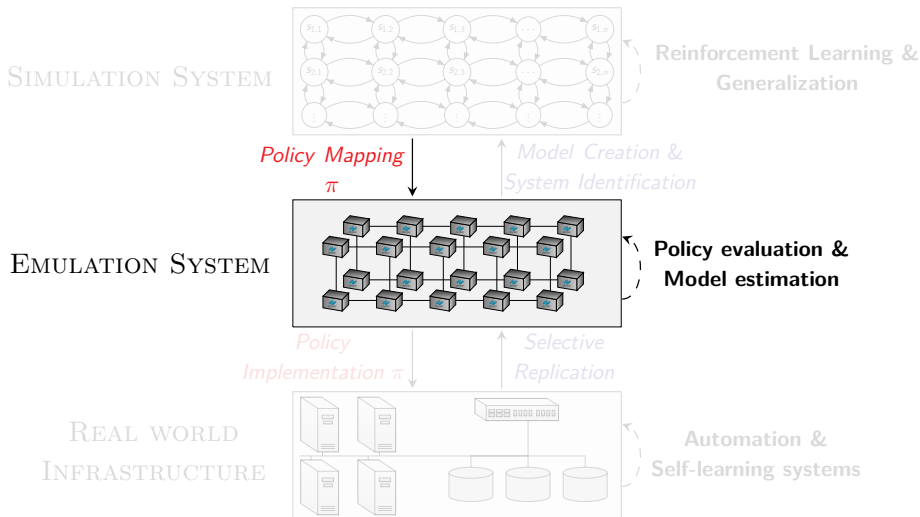
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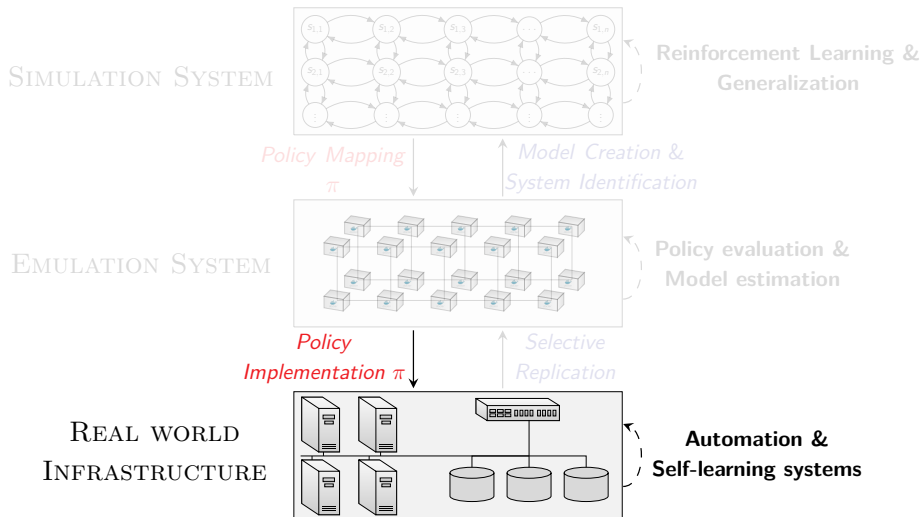
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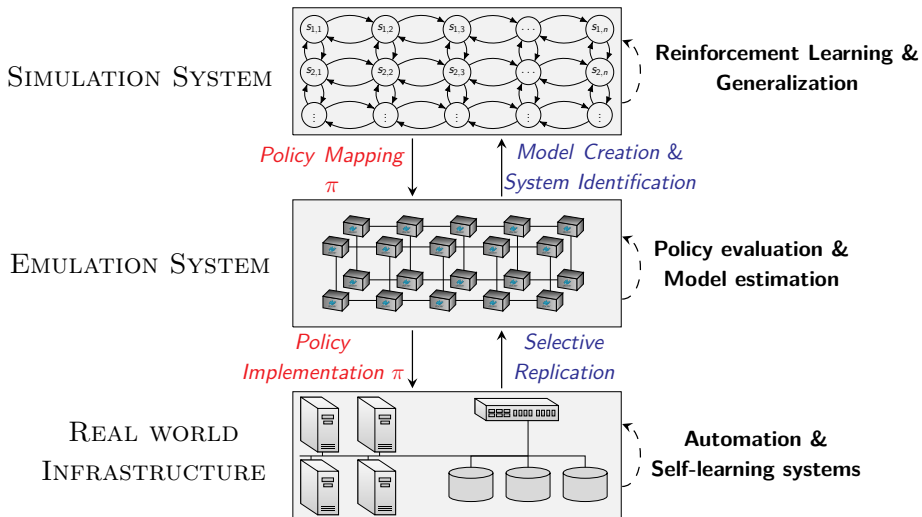
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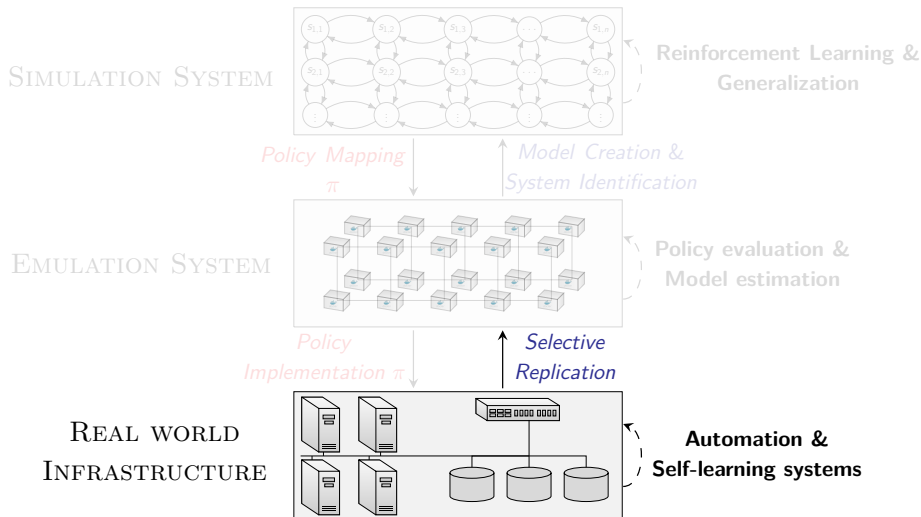
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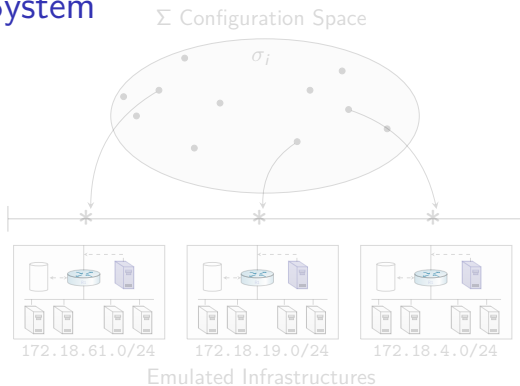
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Our Method for Finding Effective Security Strategies



Emulation System

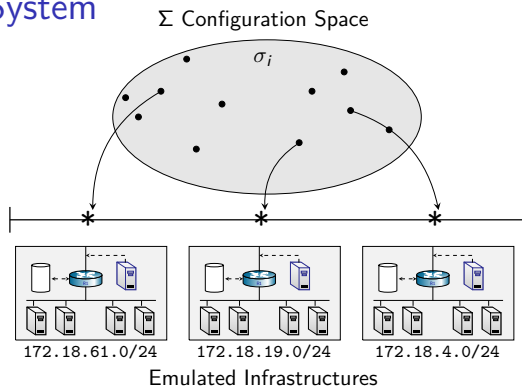


Emulation

A cluster of machines that runs a virtualized infrastructure which replicates important functionality of target systems.

- ▶ The set of virtualized configurations define a *configuration space* $\Sigma = \langle \mathcal{A}, \mathcal{O}, \mathcal{S}, \mathcal{U}, \mathcal{T}, \mathcal{V} \rangle$.
- ▶ A specific emulation is based on a configuration $\sigma_i \in \Sigma$.

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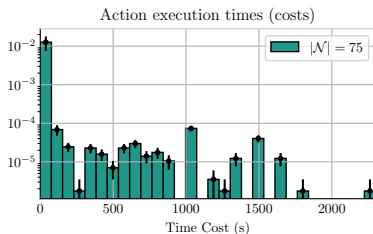
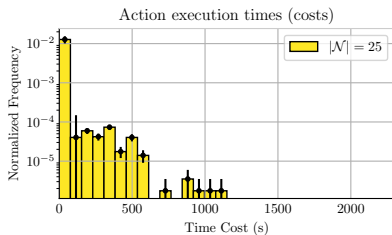


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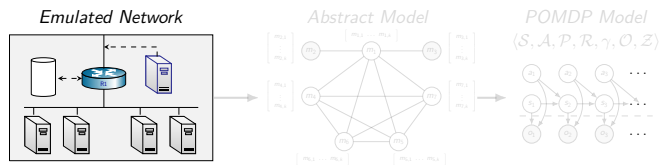
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Emulation: Execution Times of Replicated Operations



- ▶ **Fundamental issue:** Computational methods for policy learning typically require samples on the order of $100k - 10M$.
- ▶ \implies **Infeasible** to optimize in the emulation system

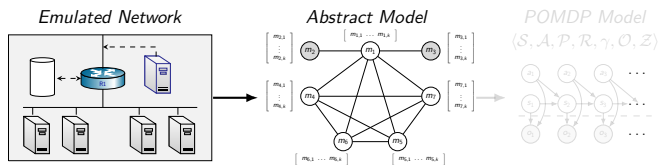
From Emulation to Simulation: System Identification



- ▶ **Abstract Model Based on Domain Knowledge:** Models the set of *controls*, the *objective function*, and the *features* of the emulated network.
 - ▶ Defines the static parts a POMDP model.
- ▶ **Dynamics Model (\mathcal{P}, \mathcal{Z}) Identified using System Identification:** Algorithm based on random walks and maximum-likelihood estimation.

$$\mathcal{M}(b'|b, a) \triangleq \frac{n(b, a, b')}{\sum_{j'} n(s, a, j')}$$

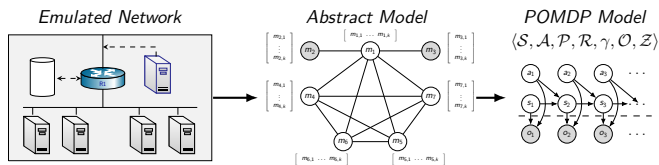
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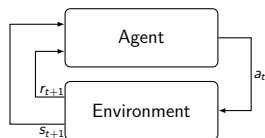
Policy Optimization in the Simulation System using Reinforcement Learning

► Goal:

- Approximate $\pi^* = \arg \max_{\pi} \mathbb{E} \left[\sum_{t=0}^T \gamma^t r_{t+1} \right]$

► Learning Algorithm:

- Represent π by π_{θ}
- Define objective $J(\theta) = \mathbb{E}_{o \sim \rho^{\pi_{\theta}}, a \sim \pi_{\theta}} [R]$
- Maximize $J(\theta)$ by stochastic gradient ascent with gradient
$$\nabla_{\theta} J(\theta) = \mathbb{E}_{o \sim \rho^{\pi_{\theta}}, a \sim \pi_{\theta}} [\nabla_{\theta} \log \pi_{\theta}(a|o) A^{\pi_{\theta}}(o, a)]$$



► Domain-Specific Challenges:

- Partial observability
- Large state space $|\mathcal{S}| = (w + 1)^{|\mathcal{N}| \cdot m \cdot (m+1)}$
- Large action space $|\mathcal{A}| = |\mathcal{N}| \cdot (m + 1)$
- Non-stationary Environment due to presence of adversary
- Generalization

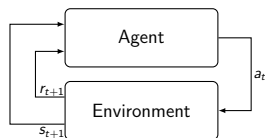
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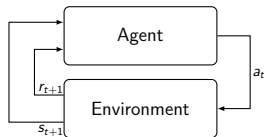
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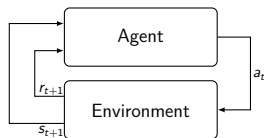
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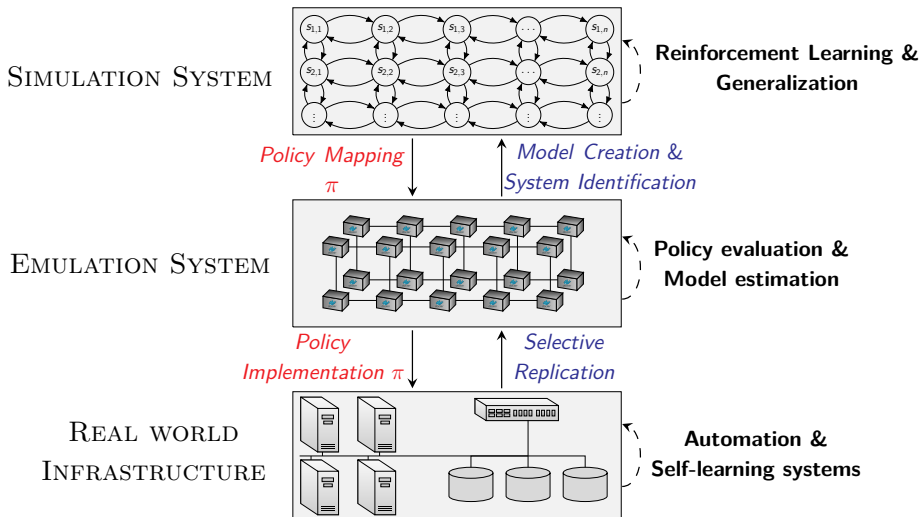
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▶ Finding Effective Security Strategies through Reinforcement Learning and Self-Play^a

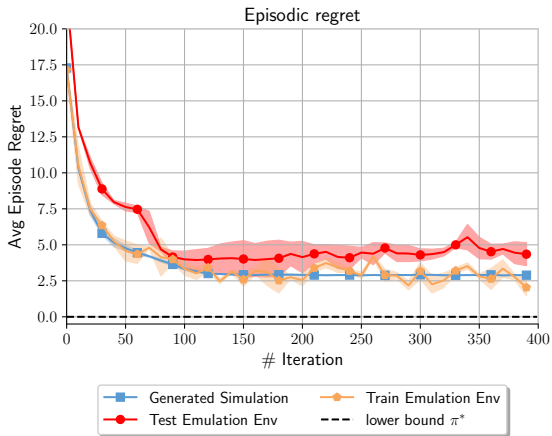


^aKim Hammar and Rolf Stadler. "Finding Effective Security Strategies through Reinforcement Learning and Self-Play". In: *International Conference on Network and Service Management (CNSM 2020) (CNSM 2020)*. Izmir, Turkey, Nov. 2020.

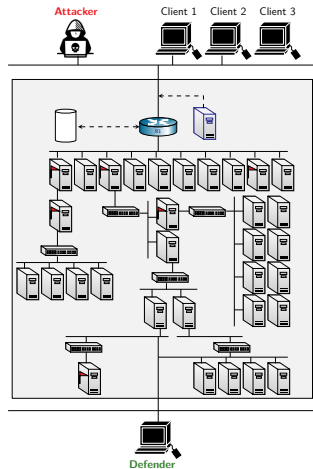
Our Method for Finding Effective Security Strategies



Learning Capture-the-Flag Strategies

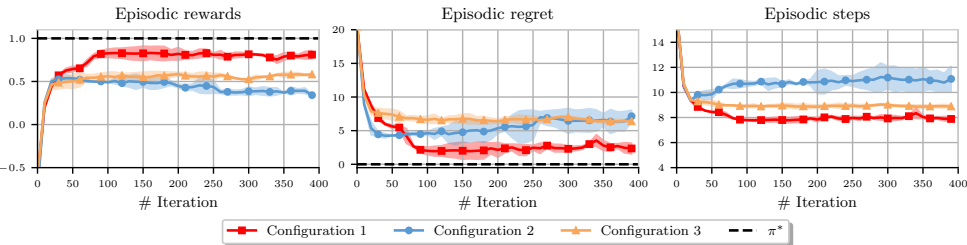


Learning curves (train and eval) of our proposed method.

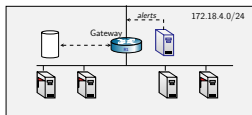


Evaluation infrastructure.

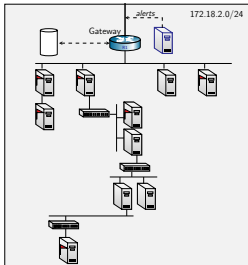
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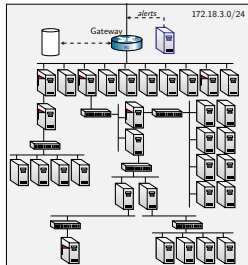
Configuration 1



Configuration 2



Configuration 3



Conclusions & Future Work

▶ Conclusions:

- ▶ We develop a *method* to find effective strategies for **intrusion prevention**
 - ▶ (1) emulation system; (2) system identification; (3) simulation system; (4) reinforcement learning and (5) domain randomization and generalization.
- ▶ We show that **self-learning** can be successfully applied to network infrastructures.
 - ▶ Self-play reinforcement learning in Markov security game
- ▶ *Key challenges*: stable convergence, sample efficiency, complexity of emulations, large state and action spaces

▶ Our research plans:

- ▶ Improving the system identification algorithm & generalization
- ▶ **Evaluation on real world infrastructures**